LV8548MCSLDGEVB

Brush DC Motor Driver Module Kit Quick Start Guide -Appendix

Arduino IDE Installation

Following process should be operated with **the Arduino Micro disconnected.**

- Run and arduino-1.8.4-windows.exe
 The installer is available in the USB drive provided in the Motor Driver Kit.
 (To avoid software from not operating properly, please use this version and refrain from updating)
- (2) Read through and agree to the terms and conditions during the setup by clicking the "I Agree" button



③Leave the following default components to install as is and press "Next"



(4) Set the install directory and press "Install"

💿 Arduino Setup: Installation Folder	-		\times
Setup will install Arduino in the following fold	ler.		
To install in a different folder, click Browse a	nd select an	other folder	
Destination Folder			
C:¥Program Files (x86)¥Arduino		Browse	
Space required: 443.1MB			
Space available: 108.3GB			
Cancel Nullsoft Install System v3.0	< Back	Ins	tall

- (5) If prompted, please install the Arduino USB Drivers:
- ✓ Arduino USB Driver
- ✓ Genuino USB Driver
- ✓ libusb-win32
- ✓ Adafruit Industries LLC Port (COM andLPT)
 - Linino Port (COM and LPT)



6 Below shows a completed installation for the Arduino IDE. Feel free to click "Close."

💿 Arduino Setu	p: Completed	_		\times
Show details				
Cancel	Nullsoft Install System v3.0	< Back	Clo	se

Supplemental GUI Content

(The following step numbers correspond to the step numbers in the "How to use the GUI" section in the Quick Start Guide)

- ③ PWM frequency
- ④ PWM mode

The input/output logic of the LV8548 is shown in the table below.

Stata	tput	Out	out	Inp
Sidle	OUT1/3 OUT2/4		IN2/4	IN1/3
Standby	Open	Open*)	L	L
Forward	L	Н	L	Н
Reverse	Н	L	Н	L
Brake	L	L	Н	Н

When all of IN1/2/3/4 are L inputs, the entire IC is in the standby state (Consumption current \approx 0). ^{*)}In the data sheet of the LV8548, it is indicated as OFF.

The graph below shows motor speed and IC surface temperature, due to ON duty. These values are tested with each PWM frequency and each PWM mode using the recommended AC adapter and the supplied reference motor.





(7) Changing GUI Language

💷 LV8548DC Fu	iction Libra	ary Test GU	I				
Language To	olTipMode	Help					
English	定——						
 ✓ 日本語 中文 			\sim	19200	~	None	
LV8714 LV8	3548DC	LV854	8Step	LV890	07 L	_V8121	LV8
_ PWM Freq	luency -				Tes	st Mode	
0.977	\sim	kHz					×
Ch1 Moto					-Ch	2 Motor	
PWM mode			~		PW	M mode	

Languages can be changed from the menu on the top left of the window.

Motor driver tab languages are not changed. (Please see tool tip for translations)

UN8548DC Fuction Library lest GUI	
Language ToolTpMode Help シリアルルート設定 V8714 LV8548DC LV854857 が LV89	Motor driver tabs are set to English
PWM Prequency 0.977 kHz -Ch1 Motor PWM mode On Dury	Test Mode Start Stop Ch2 Motor PWH mode On Dury
-10	-10 d D e +10
	Sequence lest Language: 8#.8 foelTip: API

(8) GUI Tool Tip display

The GUI sends serial data to execute API functions in the Arduino through USB.

With the API Hints turned on, hover over different buttons and settings to display descriptions and functions associated with that item.



The API hints can be turned off by navigating through the ToolTipMode menu at the top of the window



(9) Help function

From the help menu, it is possible to view GUI and API version information, as well as serial communication details.

Language	ToolTipMode	Help	Exit	-
-Serial Po	rt Settings—	A	bout	
		S	erialPort	
		_		

Selecting About will display the following window.

		Product name			
ON_MD_Module_Kit_GUI V	ersion Information	~			
	ON_MD_Module_Kit_GUI	GUI version			
	Software Version: 0.1.1.0 🍧				
	Firmware Version: LV8548DC_	Ver.1.00			
ON	Copyright (C) 2010 API	l version			
UN	ON Semiconductor				
ON Semiconductor	This software includes Prism Library. You may obtain a copy of the License at				
ON Semiconductor	http://www.apache.org/licens	es/LICENSE-2.0°.			
		J			
		<u>O</u> K			

Selecting SerialPort will display the overview of serial communication.



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(13) Arduino program code generation When using the GUI, automatically generated Arduino code will be output to the log window. It is possible to export the code to an Arduino sketch (.ino) file that can be used with the Arduino IDE.

Once the automatically generated code is imported into the Arduino IDE and uploaded to the Arduino [Micro], it is possible to mimic the procedures from the GUI.

1) <u>Generating and writing Arduino code</u> Pressing Generate Program will open a save file dialog.

٢	Log			
	SAVE	Generate Program		CLEAR
	Please s file to be Docume	select the desir e saved (e.g. D ents) and click (ed dire esktop Save.	ctory for the or

When using the GUI, So LV8548_DC_Program.ino is the name of the program, so a different name will need to be used to save the exported file.



Double click the newly saved Arduino program to open the Arduino IDE.

E-F + 60 M/ +	彩	fしいフォルダー		10	•
☆ お気に入り ■ デスクトップ	î	名前 ↓ For_DCmotor	更新日時 2017/10/05 13:04	種類 ファイル フォル	サイズ
3 最近表示した場所 タウンロード	н	For_Stepper ON_MD_Module_Kit_GUI arduino-1.8.4-windows.exe	2017/10/05 10:37 2017/10/05 11:52 2017/10/05 10:37	ファイル フォル ファイル フォル アプリケーション	92,546 KI
 ⇒イプラリ Subversion ドキュメント ビクチャ 		S Motor_test_20171128_140133.ino	2017/11/28 14:12 2017/10/05 10:37	Arduino file テキスト ドキュ	1 KI 0 KI

The GUI and Arduino IDE cannot be connected to a PC at the same time. To upload the Arduino program, please exit or select Disconnect in the GUI, and proceed working in the Arduino IDE.

Follow the instructions in the Quick Start Guide in P3 "Compiling the Arduino Program – Write to Arduino"

2) Using the generated Arduino program After each API operation in the generated program, a delay(0) is inserted. By changing the value of the argument (0) to the delay function^{*}), the user is able to freely adjust the rotation time, as well as the interval time between each API call execution. This can be used to achieve the desired stand-alone operation

```
[Example of changing the interval time]
  #include <LV8548 DC Lib.h>
  Lib LV8548DC Lib;
  void setup()
  {
    Serial.begin(19200);
    Lib. initLib();
    delay(5000); →Note
    Lib.setPWMFrequency(2);
    delay(0);//Omsec
   Lib.setRotation(0, 0);
    delay(0);//Omsec
   Lib.setCtlVoltage(0, 20);
    delay(0);//Omsec
    Lib.setStartFlag(0, 1);
    delay(5000);//Omsec
   Lib.setStartFlag(0, 0);
    delay(1000);//Omsec
"setStartFlag(0, 1)" will begin driving motor 1
"delay(5000)"
```

will drive the motor for 5000[msec] (5s)

"setStartFlag(0, 0)" will stop driving motor 1 (Open)

If the delay setting is 0 or too short, some motor operations will complete so quickly, that it will be imperceptible.

Note: The delay setting at the beginning of the setup method will execute in the case of a new USB connection, Arduino reset, or upon uploading a sketch to the Arduino. In this case, the Arduino will delay for 5 seconds while writing the initial settings.

*)delay function

When the PWM frequency is set to 0.977kHz the unit of the argument is [msec] (1000th of a second). To set a 1 second delay, use delay(1000)

The Arduino standard clock TIMER0 is affected by the API functionality of the LV8548 DC. Therefore, the timing of the delay function varies based on the PWM frequency as shown in the table below.

PWM	delay(1000)	Parameter value
frequency	execution time	for 1s delay
7.813kHz	0.125s	8000
0.977kHz	1.0s	1000
0.244kHz	4.0s	250
0.061kHz	16s	62 or 63

Board Schematics (1/2)



LV8548MCSLDGEVB Schematic

LV8548MCSLDGEVB Bill of Materials

Designator	Qty.	Description	Value	Tolerance	Footprint	Company	Part Number
IC1	1	Motor Driver	-	-	MFP10SK	ON Semiconductor	LV8548MC
R1	1	Thick Film Resistor	TBD	±5%	1608(0603Inch)		
R2	1	Thick Film Resistor	TBD	±5%	1608(0603Inch)		
C1	1	VCC Bypass Capacitor	10µF, 50V	±20%	3225(1210Inch)	Murata Manufacturing	GRM32ER71H106KA12L
CN1A, 1B	1	Pin header to baseboard	12 pins x 2	-	30.48 x 5.08	Wurth Electronik	61301221121
CN2	1	Pin header to baseboard	12 pins	-	30.48 x 2.54	Wurth Electronik	61301211121
PCB	1	PCB	-	-	30.48 x 20.32		

Parts highlighted in yellow are not mounted at the time of product shipment.

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Board Schematics (2/2)



Baseboard Bill of Materials

Designator	Qty.	Description	Value	Tolerance	Footprint	Company	Part Number
D1	1	Diode	-	-	SOD123	ON Semiconductor	MBR230LSFT1G
CN1,2	2	Arduino Micro connector	-	-	Ф1.02 x17 -2.54 pitch	SULLINS connector solutions	PPPC171LFBN-RC
CN3	1	Module connector	-	-	Ф1.02 x12 x2lines -2.54 pitch	Wurth Electronik	61302421821
CN4	1	Module connector	-	-	Ф1.02 x12 -2.54 pitch	Wurth Electronik	61301211821
CN5,7,8	3	Motor connectors	-	-	Ф1.1 x4 -3.5 pitch	Wurth Electronik	691243110004
CN6	1	Power connectors	-	-	Φ1.1 x2 -3.5 pitch	Wurth Electronik	691214110002S
J1	1	DC barrel jack	-	-	9.0 x 14.5	Wurth Electronik	694106301002
J2	1	UART pin headers	-	-	Ф1.1 x4 -2.54 pitch	Wurth Electronik	61300411121
C1	1	Electrolytic capacitor	100µF, 50V	±10%	-	Wurth Electronik	860020674015
PCB	1	PCB	-	-	80 x 60		

When using a custom-made baseboard, be sure to <u>mount an electrolytic capacitor equivalent to C1</u> <u>between VCC and GND</u>. Neglecting to install this capacitor may lead to damage and malfunction of any connected driver modules.